

367.40363X00

IN THE UNITED STATES PATENT AND TRADEMARK OFFICE

Applicant(s): OSTMAN, et al.
Serial No.: Not yet assigned
Filed: July 27, 2001
Title: METHOD AND APPARATUS FOR SYNCHRONISATION
Group: Not yet assigned



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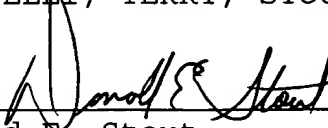
Sir:

Under the provisions of 35 USC 119 and 37 CFR 1.55, the applicant(s) hereby claim(s) the right of priority based on United Kingdom Patent Application No.(s) 0018668.4, filed July 28, 2000.

A certified copy of said United Kingdom Application is attached.

Respectfully submitted,

ANTONELLI, TERRY, STOUT & KRAUS, LLP



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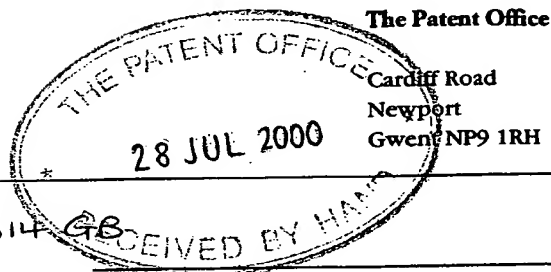
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1. Your reference

PAT 00314 GB

2. Patent application number

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0018668.4

28 JUL 2000

3. Full name, address and postcode of the or of each applicant (*underline all surnames*)

NOKIA MOBILE PHONES LIMITED
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02150 ESPOO
FINLAND

Patents ADP number (*if you know it*)

5911995004

If the applicant is a corporate body, give the country/state of its incorporation

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4. Title of the invention

METHOD AND APPARATUS FOR SYNCHRONIZATION

5. Name of your agent (*if you have one*)

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Country

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Date of filing
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Claim(s)

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METHOD AND APPARATUS FOR SYNCHRONIZATION

- 5 The present invention relates to receiver synchronisation, and more particularly to a code tracking in a CDMA system having a particular, but not exclusively, application to the field of mobile telephones.

10 In a radio communication system the symbol clocks of the transmitter (Base Station, BS) and a receiver (Mobile Station, MS) are unsynchronised. A synchronisation method for the receiver is thus needed to synchronise the symbol timing i.e. the symbol clock in a receiver to the received symbol sequence. In CDMA system the symbol synchronisation is more often called as a chip synchronisation as the synchronisation between the receiver chip
15 clock and the received chip sequence is determined. Moreover, in a CDMA system a method is needed to keep the receiver spreading sequence aligned to that of the transmitter (BS), so the method is also referred as code tracking.

The synchronisation, in general, is achieved by extracting a suitable control
20 signal from the received signal, and using a phase locked loop to keep the error between the extracted control signal and a locally generated copy of the control signal as small as possible. One such known technique is based on Delay-Locked Loop (DLL) where the combined impulse response of the transmitter filter, communication channel and receiver filter is computed in the
25 receiver based on the received signal. DLL then tries to minimise the difference between the delay of the channel and the reference delay of the locally generated impulse response.

One known DLL tracking method is called as Early-Late DLL method where
30 one sample of the impulse response is calculated half of a chip earlier and

- another sample is calculated one half of a chip later than the desired sampling point. Another method, called as Early-On-time DLL, is known from US 5,590,160 where one sample of the impulse response is calculated half of a chip earlier than the desired sampling point and another sample is calculated at the desired sampling point. DLL is then using those sample values in phase locked loop to control the synchronisation timing. In US 4,590,160 it is disclosed a DLL operation where the ratio of those samples is compared to a reference ratio, and the result is used as an error signal for phase locked loop.
- One problem in a wireless communication relating to synchronisation is the multipath propagation. In that situation the received signal is a superposition of several versions of the transmitted signal, delayed by various delays the signal copies having random phases and amplitudes. The impulse response is consequently also a superposition of several versions of the combined transmitter and receiver impulse responses, which means that the original impulse response is distorted by this superposition. This distortion is particularly difficult if the delay between two or more impulse response copies is between 0.2 – 2 symbols (or chips in CDMA). This condition is commonly known as a "fat finger" case. If the delay difference is smaller than 0.2 symbols (chips), the impulse response is not that much distorted but this case can cause a situation called flat fading where different signal copies cancel each other out. On the other hand, if the delay is more than 2 symbols, the copies of the impulse response do not effect each other much and the combined impulse response may be viewed as two separate impulse responses.

In US 5,590,160 the Early-On-time DLL is used in a spread spectrum receiver where the receiver consists of a several receivers, known as fingers. Each finger is used to demodulate its own version of the delayed signal, and the output from the individual fingers is coherently combined. This type of receiver

is commonly known as a RAKE receiver. In a RAKE receiver the DLL is used to lock each separate finger to a distinguishable signal copy. However, when the above mentioned fat finger case happens neither Early-On-time nor Early-Late DLLs can provide optimal operation since they do not allow all of the energy in the fat finger to be demodulated. The problem is that DLLs in each finger are locking the fingers to the same position, thus providing no gain. In other words, although these different DLLs (Early-On-time and Early-Late DLLs) are locking on to different places of the fat finger the demodulated energy is however roughly equal in both cases.

10

According to a first aspect of the present invention there is provided a method for synchronising a receiver where the method comprises steps of:

tracking the received signal by a first receiver branch using a first tracking method the signal being sampled at first sampling time;

15 tracking a delayed version of the received signal by a second receiver branch using said first tracking method, the signal being sampled at second sampling time;

detecting the delay between the received signal and its delayed version;

comparing the delay with a pre-determined threshold and in the case when

20 the delay falls below the threshold, tracking the delayed version of the received signal by a second tracking method.

According to a second aspect of the present invention there is provided a

device for synchronising a receiver comprising: a converter for sampling the

25 received signal and its delayed version, a first receiver branch for tracking the received signal using first tracking method the being signal sampled at first sampling time, a second receiver branch for tracking a delayed version of the received signal using said first tracking method the signal sampled at a

second sampling time, a means for determining the delay between the

30 received signal and its delayed version, means for comparing the time delay

with a pre-determined threshold and means for changing the tracking method for the delayed version of the received signal to a second tracking method.

The present invention provides a method in which two fingers of a RAKE receiver can be locked to a multipath received signal in a way which enables an improved demodulation, specially in fat finger case mentioned above. In the case of fat finger impulse response, one embodiment of the present invention assigns two RAKE fingers to a fat finger impulse response; One finger tracking the impulse response with Early-Ontime DLL method and the other finger tracking the impulse response with Ontime-Late DLL method. This has an advantage that DLL loops keep the RAKE fingers as apart as possible, which means that the correlation between the signals that each finger is demodulating is minimised. In other words, this means that these two fingers are capable of demodulating the signal energy at different position of a signal in a fat finger impulse response.

In a further embodiment of the invention it is presented a way to allocate more than two fingers to sample the multipath received signal in a fat finger impulse response situation. In one modification the first finger is tracking the rising edge of the impulse response (Early-Ontime DLL) and the second finger is tracking the falling edge (Ontime-Late). The further one or more intermediate fingers are then positioned to a predetermined distance from the finger tracking the rising edge. The intermediate finger(s) are thus having their DLLs disabled. It further characteristics that the intermediate finger(s) follow the position of the Early-Ontime finger as the DLL in Early-Ontime finger is changing the position of the leading finger. In this situation the position of the intermediate finger(s) is changing by the same amount. In a second modification there is no finger allocated for the falling edge of the fat finger impulse response, but there is only one finger tracking the rising edge (Early-Ontime) and all other fingers are set to follow that tracking finger. This

allocation of further fingers is advantageous in the case where the shape of impulse response estimate is fat enough that the demodulation can be improved allocating more than two fingers to the impulse response.

- 5 Exemplary embodiments of the invention are hereinafter described with the reference to the accompanying drawings, in which:

Figure 1a shows a symbol waveform with different sampling points;

Figure 1b shows a fat finger impulse response situation;

- 10 Figure 2 shows a block diagram of a radiotelephone utilising the invention

Figure 3 shows a block diagram of an apparatus of the present invention;

Figure 4 shows a block diagram of a matched filter;

Figure 5 shows a flow diagram in accordance with the present invention;

Figure 6 shows a diagram illustrating an implementation of the present

- 15 invention;

Figure 7 shows a flow diagram illustrating the finger allocation in accordance with the present invention;

Figure 8 shows a second flow diagram illustrating the finger allocation in accordance with the present invention.

- 20

Figure 1a shows one example of the received sample signal 10 and sampling pulses 11, 12, 13 in different location of the sample signal. In Early-On-time method the sampling is ideal, i.e. the synchronisation is reached, at time instants 11 and 12. In Early-late method the sampling is correspondingly done at time instants 11 and 13. The sampling times are separated by a $\frac{1}{2}$ chip period.

25

Figure 1b shows the impulse response estimate in a fat finger situation. This figure shows a case where the difference between the impulse response

peaks is 1 symbol time (1 chip) so that the impulse responses 14, 15 are partly aligned.

Figure 2 shows a block diagram of a radiotelephone employing the synchroniser according to the present invention. In this description the reference is only made to reception path of the signal as it will be clear to those skilled in the art that approximately the same steps occur in the transmission path, but in a reverse order. First the antenna 21 provides the input to RF block 22 which performs the necessary filtering operations and down-converts the received RF signal, in one or more steps, to a lower frequency and to be processed in baseband 24. At reception branch an A/D conversion is applied to a signal to enable digital signal processing in baseband 24. Baseband processing 24 comprises the receiver blocks including the RAKE receiver, detection and the synchronisation referred in this invention. The reception branch further includes blocks (not shown in the figure) like decryption, de-interleaving, channel decoding and speech decoding after which the received speech/data is output to the user.

Figure 3 shows in more detailed one embodiment of receiver of the present invention. The received signal typically comprises signals described as I and Q components. However, here for the clarity, only one of the branches is shown. The signal 301 from the RF is first converted to digital presentation by an A/D converter 23. The telecommunication system where the apparatus of present invention is operable can be based on a chip rate of e.g. 4.096 Mchip/s. The A/D converter 23 is then using a certain number of clock cycles per chip, e.g. 8 samples/chip, to sample the received signal 31. The sampled digital signal 24 is then input to a matched filter 303 and stored to finger input register 304 from which the digital samples are selected to corresponding fingers as described later in detailed. The amount of fingers (N in figure 3) in the RAKE receiver is an implementation issue, N being e.g. 5.

Referring now to figure 4, one example of a matched filter 400 of figure 3 is described in more detailed. The matched filter includes two registers; a register 401 receives the digital samples 24 from the A/D converter 23. The register size may be e.g. 127 samples. Register 402 stores a predefined code/data, which is searched from the incoming data 23. The matched filter further includes multiplying units 403 and a summing unit 404 for determining the correlation between the received data 23 and the pre-stored code in register 402. The matched filter outputs a signal 405 estimating the impulse response for the received signal 23, which shows peaks when the pre-stored data equals the received data. These different peaks correspond to the different multipath received signal components. Correlation calculation done by the matched filter can be presented as follows:

$$y(t) = \frac{1}{N} \sum_{n=1}^N x(t - nT_s) s(n)$$

where the N is register length (e.g. 127), T_s is sampling period, $s(n)$ is the prestored code and $x(t)$ is the incoming data from A/D converter.

In figure 3 signal from the matched filter 303 is provided to peak detector block 305, which stores the signal from the matched filter 303 and determines locations of the peaks corresponding to the multipath delays. The peak detector 305 can be implemented by a register or memory, which stores the samples from the matched filter 303. Known DSP (Digital Signal Processing) functions/algorithms can then be utilised to search the peaks and the corresponding locations. Peak detector 305 outputs a digital signal 306 indicative of a time delay between different multipath signals i.e. time between the peaks. In other words, the signal indicates the difference between peaks 1 and 2, 2 and 3, and so on. Those time differences are then utilised in

threshold comparator 307, which determines whether any of those time differences falls below a certain threshold. When it is detected that the threshold is not met a signal 308 is output to finger allocation unit 309 which causes to change the sampling times of corresponding RAKE finger. For
5 example if the time difference between 3rd peak and 2nd peak falls below the threshold then the tracking method of the finger 3 is changed as described further in this specification (assuming that the finger 3 is tracking the 3rd peak). In other words, the finger allocation unit has a control to select by a signal 310 from the finger input register 304 the right signal samples to be used by the
10 fingers so that certain samples are used in code tracking in certain RAKE fingers as described further in figure 5. The operation of threshold comparator and the finger allocation unit can be implemented by using DSP's existing arithmetical operations.

15 Figure 3 also shows an alternative way to implement the present invention. In this embodiment of the present invention the finger position information 311 – 313 from finger position counters 314 – 316 within each RAKE finger are used by the threshold comparator 307 to detect the positions of the fingers and to determine whether the time difference between the location of the fingers falls
20 below a certain threshold. The finger position information 311 – 313 is also provided to finger allocation unit 309 which allocates the fingers according to present invention as described later in this specification. If having e.g. 8 samples/chip, as in the example above, then each finger position is known by the accuracy of 1/8 chip. One way to implement the position counter is
25 presented in US 5,590,160.

Signal samples from the A/D converter 23 are also provided to the RAKE receiver having a certain amount N of fingers 317(1) – 317(N) for tracking the received multipath signals. The different demodulated and despread
30 multipaths of the same signals 318 – 320 are then combined in the combiner

321 in order to receive maximum energy to be used by the detector of a receiver. The detected data 322 is then further provided to de-interleaving (not shown in the figure).

- 5 Figure 5 shows a flow diagram of the method according to one embodiment of the present invention. The procedure is started by the step 500 where the time difference between the different impulse response estimates is determined. At the starting step the fingers of the RAKE receiver are operating by using Early-Ontime or Early-Late principles described earlier. If
- 10 the delay between the impulse response estimates is between 0.2 – 2 symbols (chips) a fat finger state 501 is detected. If the decision was negative it is then determined at step 502 whether the delay is over 2 samples which means that estimated impulse responses are virtually non-overlapping and can be regarded as a separate impulse responses and the state 503 is
- 15 detected. If the decision at block 502 is negative which means that the delay is less than 0.2 symbols no actions are needed to change the sampling timing of the RAKE fingers and the procedure enters the starting point 500. When the fat finger state is detected at 501 the tracking method of at least one the RAKE fingers is changed at 503. According to one embodiment of the
- 20 invention the tracking in first finger is done to using Early-Ontime principle and the tracking in second finger is done using Ontime-Late principle.

- Figure 6 shows one embodiment of the invention, which clarifies more the operation of the block 503 in figure 5. At the starting point when the fat finger
- 25 state is not detected fingers of the RAKE receiver are operating based on Early-Ontime or Early-late principle. For example let's have an example where the Early-Ontime is used and the A/D converter is outputting 8 (0 - 7) samples per chip. In this case the sampling for the finger 1 at a certain time instant can be such that the early sampling is done at the sample number 7(chip n-1) and
- 30 the on-time sampling is done at sample number 3(chip n). Finger 2 may then

have e.g. early sampling at sample number 0 and the On-time sampling at sample number 4 (e.g. during chip $n+3$). Finger 3 then may have again a different sampling timing depending on the multipath signal that finger is tracking. When the detection is done based on the signal from the matched filter or based on the information from finger position counters that the time delay between the impulse response estimates falls below a certain time limit (e.g. 2 chips), the tracking method of one of the fingers is changed. According to one embodiment the tracking method of one finger is changed. Here in our example the tracking of the finger 2 is then changed from Early-Ontime to Ontime-Late so that the on-time sampling would be then e.g. at sample number 4(chip $n+1$) and the late sampling at sample number 0 (chip $n+2$). In other words, in this example the time delay between the tracking fingers 1 and 2 during the fat finger state is $1 \frac{1}{8}$ of chip period.

Figure 7 below shows a flow diagram another embodiment of the present invention where more than two fingers are allocated to a fat finger impulse response. First it is determined at step 701 if the distance between two fingers allocated to a fat finger is much more than 1 chip; e.g. 1,5 of chip period. If the answer is positive then one or more further finger is allocated at step 702 to a fat finger impulse response. In this case the first finger is tracking the rising edge of the impulse response by Early-Ontime DLL method and the second finger is tracking the falling edge of the fat finger impulse response by Ontime-Late method as described earlier. In this embodiment of the invention one or more further fingers are allocated to follow the position of the first finger so that a predetermined distance is used between the first and one or more intermediate fingers. For example let's have situation, where finger 1 is having samples 7 (chip $n-1$) and 3 (chip n) for Early and Ontime samples and finger 2 is having samples 2 (chip $n+2$) and 6 (chip $n+2$) for Ontime and Late samples. In this case difference between the Ontime samples of finger 1 and finger 2 is 15 samples. Now, according to this

embodiment of the invention one or more fingers can be allocated to sample during this 15 samples (i.e. $1 \frac{7}{8}$ of a chip period). For example, a 3rd finger can be allocated to sample at sampling time 3 (chip $n+1$) so the sampling for that finger would be a predefined as 8 samples later than the Ontime

5 sampling for finger 1. Alternatively, if allocating two intermediate fingers (fingers 3 and 4), then the sampling for finger 3 could be defined e.g. 5 samples after Ontime sampling (i.e. sample 0 (chip $n+1$)) of finger 1 and the sampling for finger 4 would then be 10 samples from the Ontime sampling point of finger 1 (sample 5 (chip $n+1$)). In a similar way more than 2

10 intermediate finger can also be allocated.

Still one more modification is possible where no fingers are set to track the falling edge (or rising edge) of the fat finger impulse response. In this case one finger is tracking the rising edge (or falling edge) and all other fingers are

15 set to follow the tracking finger in the manner described earlier.

Figure 8 shows still one embodiment of the present invention where the positions of the RAKE fingers monitored by using the position counters in figure 3 or by detecting the peaks from the matched filter. At step 801 it is

20 determined if the fingers are detected to get too close to each other e.g. less than $1/8$ of a chip, it is determined at 802 that the impulse response is not of a fat finger type. In this case one of the fingers allocated for the fat finger is removed at step 803. Now, If a multipath is detected at 804, that is not demodulated by a finger and the power of the multipath exceeds a

25 predetermined threshold (step 805), the de-allocated finger is assigned to this multipath.

In the view of foregoing description it will be evident to a person skilled in the art that various modifications may be made within the scope of the present

30 invention.

CLAIMS

5

1. A method for synchronising a receiver where the method comprises steps of:

tracking the received signal by a first receiver branch using a first tracking method the signal being sampled at first sampling time;

10 tracking a delayed version of the received signal by a second receiver branch using said first tracking method, the signal being sampled at second sampling time;

detecting the delay between the received signal and its delayed version;

comparing the delay with a pre-determined threshold and in the case when

15 the delay falls below the threshold, tracking the delayed version of the received signal by a second tracking method.

2. A method according to claim 1, characterised in that, the first tracking method is tracking the rising edge of an impulse response estimate.

20

3. A method according to claim 1, characterised in that, the second tracking method is tracking the falling edge of an impulse response estimate.

4. A method according to claim 1, characterised in that the method further
25 comprises steps of: comparing the time difference with a second threshold and in the case when the time difference exceeds the second threshold, allocating a third receiver branch for sampling the received signal at a third sampling time other than the first and second sampling times.

5. A method according to claim 4, characterised in that, the third sampling is occurring at a pre-determined time from the first sampling time.
6. A method according to claim 4 or 5, characterised in that, the third sampling
5 time is a sampling occurring at a pre-determined time, said time being before said second sampling time.
7. A method according to claim 4, characterised in that the method further comprises allocating a fourth receiver branch for sampling the received signal
10 at a fourth sampling time other than the first, second and third sampling times.
8. A method according to claim 1, characterised in that, the detecting the delay between the received signal and its delayed version comprises a determination of the correlation between the received signal and a predefined
15 code.
9. A device for synchronising a receiver comprising: a converter for sampling the received signal and its delayed version, a first receiver branch for tracking the received signal using first tracking method the being signal sampled at
20 first sampling time, a second receiver branch for tracking a delayed version of the received signal using said first tracking method the signal sampled at a second sampling time, a means for determining the delay between the received signal and its delayed version, means for comparing the time delay with a pre-determined threshold and means for changing the tracking method
25 for the delayed version of the received signal to a second tracking method.
10. A device according to claim 9, characterised in that, the device further comprises means for comparing the time difference with a second threshold, and means for allocating a third receiver branch, in the case when the time

difference exceeds the second threshold, for sampling the received signal at a third sampling time other than the first and second sampling times.

11. A device according to claim 10, characterised in that the device comprises
- 5 means for allocating a fourth receiver for sampling the received signal at a fourth sampling time other than the first, second and third sampling times.

ABSTRACTMETHOD AND APPARATUS FOR SYNCHRONIZATION

The present invention provides a method and a device in which two or more
5 fingers of a RAKE receiver can be locked to a multipath received signal in a
situation of fat finger impulse response. One embodiment of the present
invention assigns two RAKE fingers to an impulse response so that one finger
is tracking the impulse response with Early-On-time DLL method and the other
finger is tracking the impulse response with On-time-Late DLL method. The
10 method comprises detecting the delay between the received signal and its
delayed version, comparing the delay with a pre-determined threshold and in
the case when the delay falls below the threshold, changing the tracking
method of the delayed version of the received signal to a second tracking
method.

15

Figure 3

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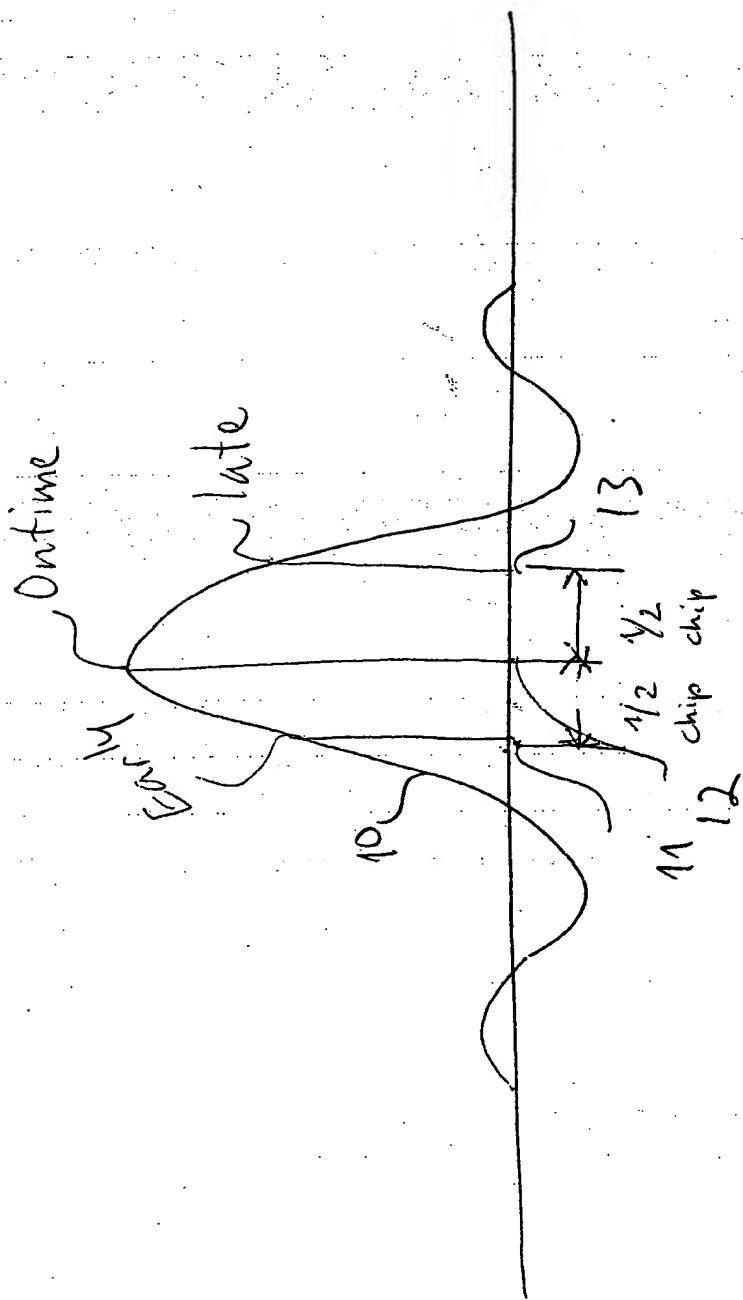


Fig 1a

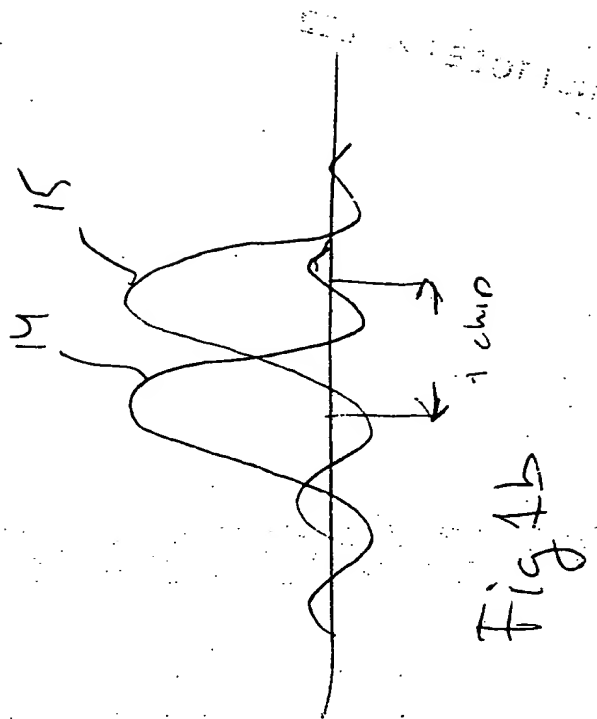


Fig 1b

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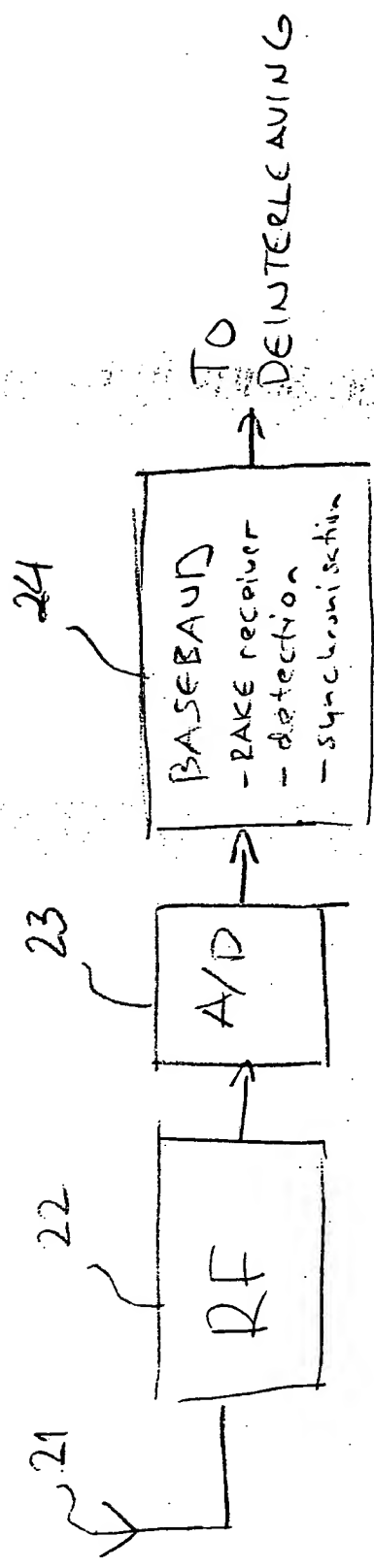


Fig. 2

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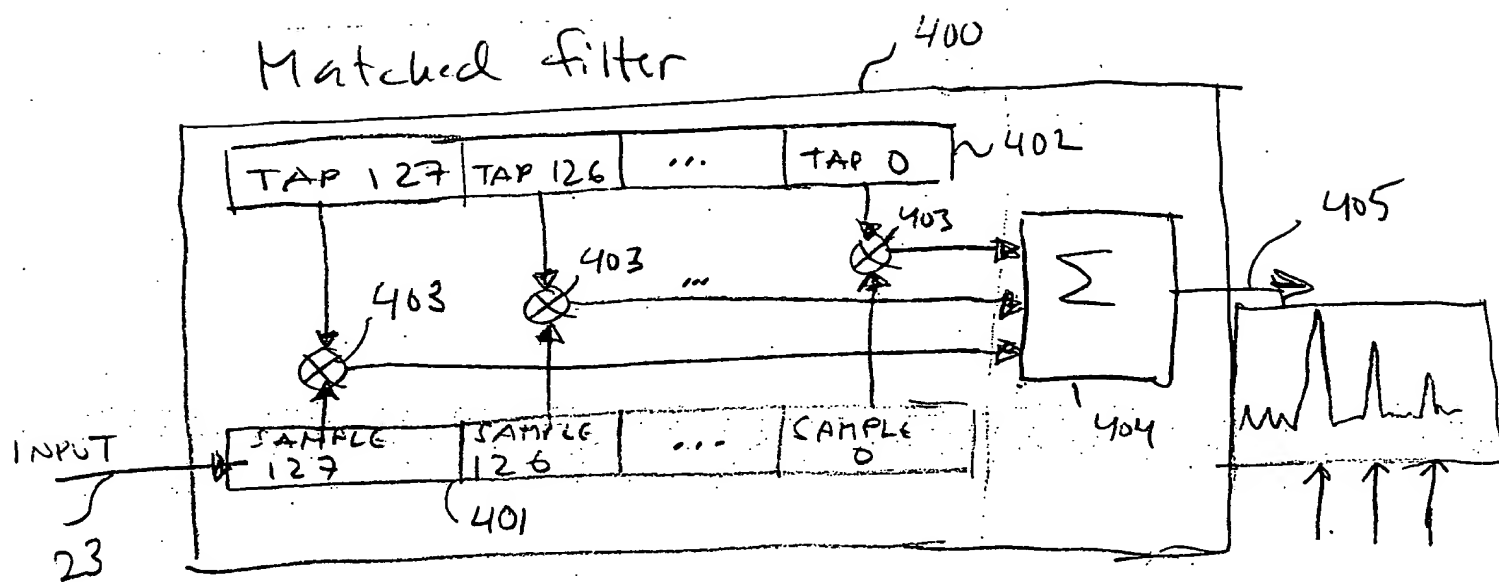


Figure 4

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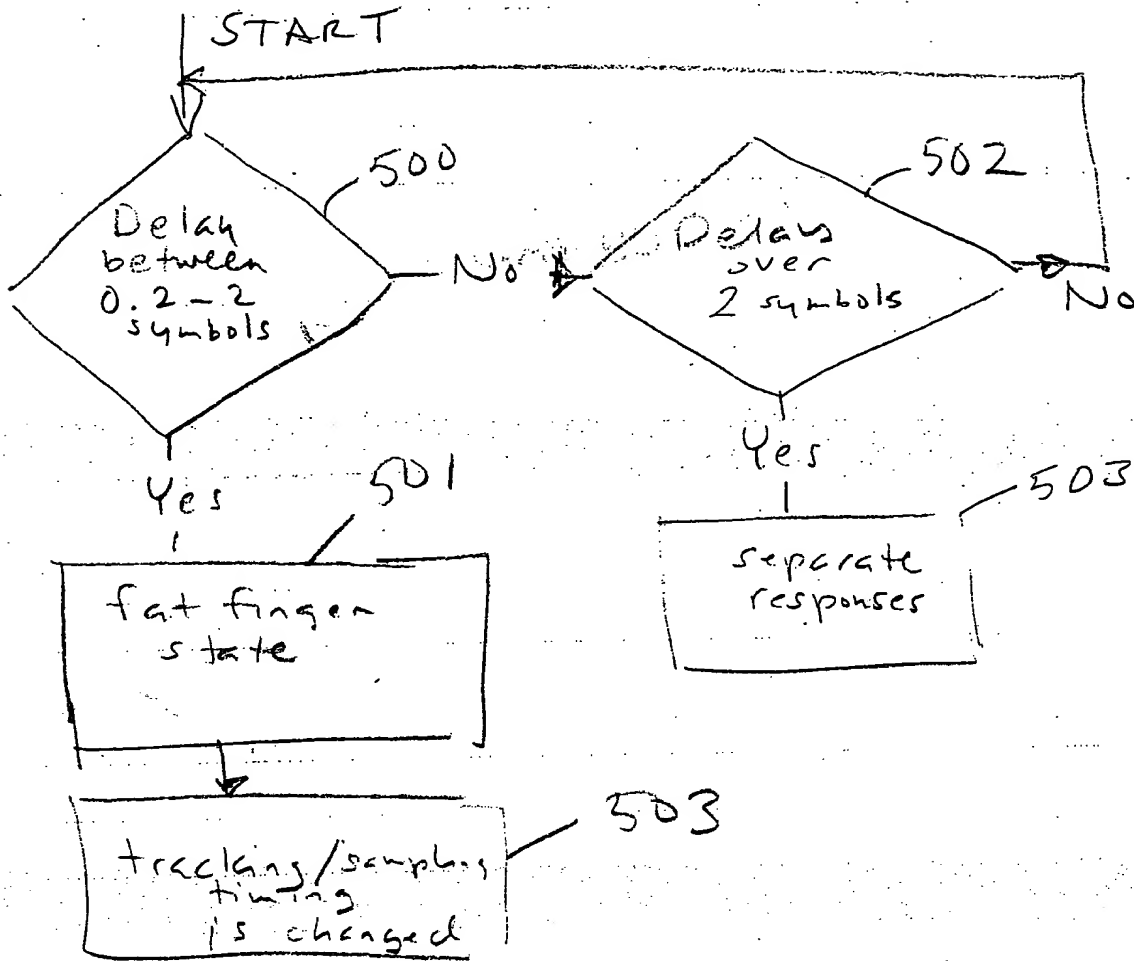


Fig 5.

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NOT A FAT FINGER STATE

FINGER 1:

Early: 7 (chip $n-1$)
Online: 3 (chip n)

FINGER 1

Early: 7 (chip $n-1$)
Online: 3 (chip n)

FINGER 2:

Early: 0 (chip $n+3$)
Online: 4 (chip $n+3$)

FINGER 2

Online 4 (chip $n+1$)
Late 0 (chip $n+2$)

FAT FINGER
STATE
DETECTED

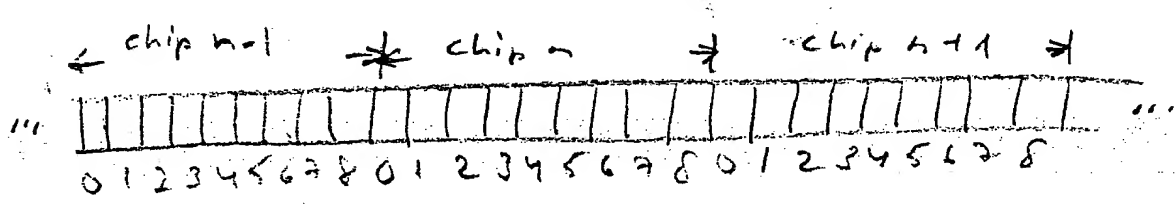


Fig. 6.

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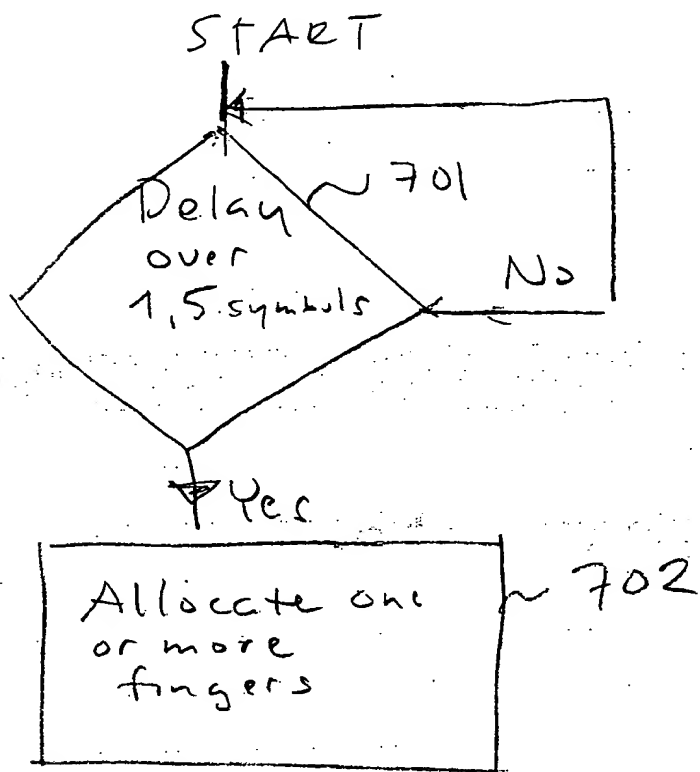


Fig. 7

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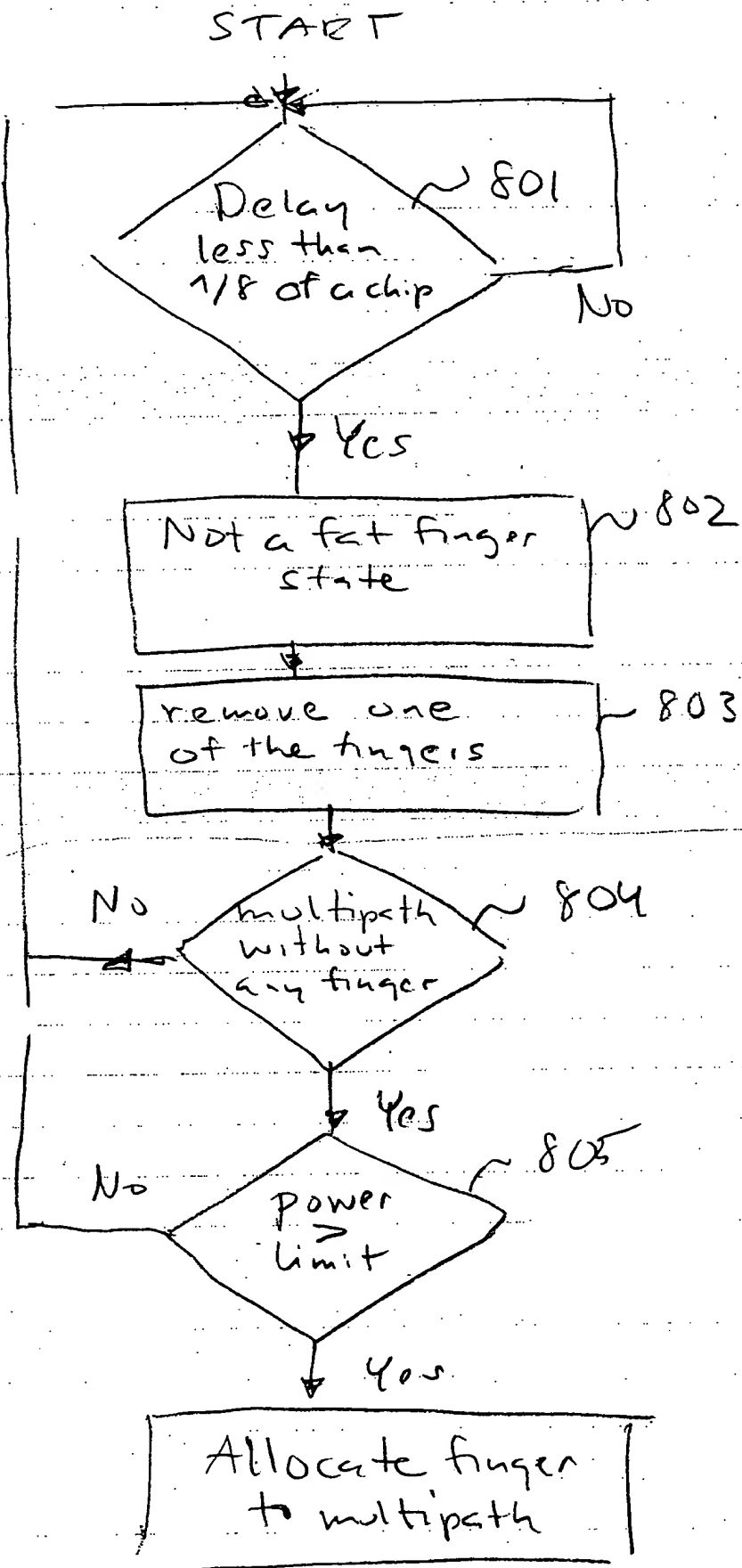


Fig. 8

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